

An Adaptive Data Analysis Method for nonlinear and Nonstationary Time Series: The Empirical Mode Decomposition and Hilbert Spectral Analysis

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Abstract

An adaptive data analysis method, the Empirical Mode Decomposition and Hilbert Spectral Analysis, is introduced and reviewed briefly. The salient properties of the method is emphasized in this review; namely, physical meaningful adaptive basis, instantaneous frequency, and using intra-wave frequency modulation to represent nonlinear waveform distortion. This method can perform and enhance most of the traditional data analysis task such as filtering, regression, and spectral analysis adaptively. Also presented are the mathematical problems associated with the new method. It is hope that this presentation will entice the interest of the mathematical community to examine this empirically based method and inject mathematical rigor into the new approach.

1. Introduction

Data analysis is necessary for science and engineering, for data is the only link we have with the reality. Consequently, data analysis serves two purposes: First, it provides validation of our theories or models. Second, it provides the guide of the underlying mechanisms as a base for discovery, creation or improvements of the theories and models. Either way, the data contains information we are seeking; the goal of data analysis is to find the information in the data. As one does not have a complete knowledge base of the underlying mechanisms for most of the physical problems we face today, one should inject as little subjective specifications as possible in the process of data analysis, so that we do not prejudice the results. A truly objective data analysis method should be adaptive to the data and let the data set speaks for itself.

Traditional time-frequency analysis methods, however, all follows the well established mathematical rules: the methods all start with a definition of a basis, and convolve the signal with the basis to get amplitude and frequency either for distributions or for filtering. Such an approach has the great advantage of having a solid mathematical foundation. Once the algorithm is established, data analysis can go forward mechanically. Unfortunately, within the comfortable fold of solid mathematic foundation, the methods can not be adaptive at all. Furthermore, this well trodden path also restricts the methods developed under this paradigm to linear and stationary assumptions.

As data can come from all sources ranging from relatively well established physical sciences, to complicated biologic processes and social-economic phenomena., most of the driving mechanisms are so complicatedly intertwined and interacting that the data one obtained are also highly variable, not only from one case to another but also from time to time even limited to one single case. In other words, one has to face data from nonlinear and non-stationary processes. This requirement is known for a long time, but remedy is slow to come. To accommodate for data from non-stationary processes, one has met many success. Methods (see for example, Flandrin, 1999) such as spectrogram, Wigner-Ville distribution, Wavelet analysis are all examples. To

accommodate for data from non-linear processes, however, progress has been very slow. The available methods (see, for example, Tong, 1990, Krantz and Schreiber, 1997 and Diks, 1998) are limited to handle data from deterministic low dimensional chaotic systems.

Even for data from non-stationary processes, the available methods are also limited to linear systems, for the methods were mostly based on the well established *a priori* basis approach, where all the analysis is based on convolution of the data with the established basis. This approach, unfortunately, has drained all the physics out of the analyzed results, for any *a priori* basis could not possibly fit all the variety of data from drastically different underlying driving mechanisms. Any misfit will automatically be assigned to the various orders of harmonics with respect to the selected basis. Though results so obtained satisfy the mathematical requirements, they lack physical meaning. Furthermore, the convolution processes involve integration, which make the results suffering the limitation imposed by the uncertainty principle, and preventing us from examine the details of the data and their underlying mechanisms.

Let us take a simple example to examine the characteristics of data from a nonlinear system. Consider the Duffing equation without damping given as

$$\frac{d^2x}{dt^2} + x + \varepsilon x^3 = \gamma \cos \omega t \quad , \quad (1)$$

where ε is a parameter, not necessarily small; γ is the magnitude of the driving force. We can easily rewrite this equation slightly as follows:

$$\frac{d^2x}{dt^2} + x (1 + \varepsilon x^2) = \gamma \cos \omega t \quad . \quad (2)$$

If one treats the quantity in the parenthesis as a single number designated as L:

$$L = 1 + \varepsilon x^2 \quad , \quad (3)$$

then the quantity L can be treated as the pendulum length or the spring constant. Either way, L changes with position; therefore, the frequency of the system should also change with position even within one oscillation period. Such intra-wave frequency modulation is the special characteristics of a nonlinear system; and it

requires a detailed frequency representation that is unattainable from a *a priori* basis approach. For example, following the classic perturbation analysis by imposing a linear structure on a nonlinear system, one would find the solution consisted of endless harmonics. The effect of the harmonics is to find enough sinusoidal components to fit the deformed final waveform, commonly known as harmonic distortions. It is well known that each term in this perturbation solution does not have physical meaning, only the summation of all the terms represents the physics. But using any *a priori* basis analysis, one would inevitably obtain a collection of the harmonics of one form or the other depending on the basis function selected; thus rendered the interpretation of spectral analysis problematical. The harmonics representation here is a poor substitute of the detailed instantaneous frequency description of the intra-wave frequency modulation. But such a detailed description will call for a drastic new approach. In fact to describe intra-wave frequency modulation, one cannot use *a priori* basis approach. An easy alternative is to use the Hilbert Transform, which is defined as

$$y(t) = \frac{1}{\pi} P \int_{-\infty}^{\infty} \frac{x(\tau)}{t - \tau} d\tau, \quad (4)$$

in which $x(t)$ is the given function of L^p class, $y(t)$ is the Hilbert transform, which is the complex conjugate of $x(t)$, and P indicates the principal value of the singular integral. As $y(t)$ is the complex conjugate, one has

$$z(t) = x(t) + j y(t) = a(t) e^{j\theta(t)}, \quad (5)$$

where

$$a(t) = (x^2 + y^2)^{1/2}; \quad \theta(t) = \tan^{-1} \frac{y}{x}. \quad (6)$$

Here a is the instantaneous amplitude, and θ is the phase function; thus the instantaneous frequency, with the stationary phase approximation, is simply

$$\omega = \frac{d\theta}{dt}. \quad (7)$$

This definition also coincides with the classical wave theory. This definition of instantaneous frequency appears to be local, for it is defined through differentiation rather than integration, and hence, the resulting instantaneous frequency may be able to describe the intra-wave frequency modulation. This approach has been recommended by Hahn (1996) for applications signal processing. Unfortunately, this straightforward and simple-minded approach does not work well. Although the Hilbert transform is valid under a very general condition, for the instantaneous frequency derived from the above approach to make physical sense, the function has to be ‘mono-component’ as discussed by Cohen (1995) and Huang et al. (1998, 1999). This has been illustrated by Huang et al (1998) with a simple function as

$$x(t) = a + \cos \alpha t, \quad (8)$$

with a as an arbitrary constant. Its Hilbert transform is simply

$$y(t) = \sin \alpha t; \quad (9)$$

therefore, the instantaneous frequency according to Equation (7) is

$$\omega = \frac{\alpha (1 + a \sin \alpha t)}{1 + 2a \cos \alpha t + a^2}. \quad (10)$$

Equation (10) can give any value for the instantaneous frequency, depending on the value of a . In order to recover the frequency of the input sinusoidal signal, the constant has to be zero. This simple example illustrates a crucial condition for the Hilbert Transform approach to work here: the function will have to be zero mean locally. This seemingly trivial condition has created great misunderstanding, which has prompted Cohen (1995) to list a number of ‘paradoxes’ concerning instantaneous frequency. Some of the paradoxes concerning negative frequency are direct consequence of this condition.

Another obvious consequence of this condition is the difficult experience by all previous attempts to use the Hilbert transform: how to reduce or decompose an arbitrary function to a ‘mono-component’ one with local zero mean? And more fundamentally, if the function is non-stationary, how can one find the local mean? These difficulties have forced the past applications of Hilbert transform to extract a narrow band component with a band-pass filter on the original data (Melville, 1983). As the band-pass filter is a linear operator, any signal passing through it will lost all its ‘harmonics’, and suffer deformation of the fundamental wave shape. Such approach certainly satisfies the condition demanded by the instantaneous frequency computation through Hilbert transform. However, it has unwittingly drained some interesting information from the data, the nonlinear characteristics associated with the signal.

With all these difficulties, the real applications of Hilbert transform will have to wait for the development of the Empirical Mode Decomposition (EMD) (Huang et al. 1998, 1999, 2003). Together with the Hilbert Spectral Analysis (HSA), the combination established a new adaptive time-frequency analysis method.

2. The Empirical Mode Decomposition and Hilbert Spectral Analysis

The details of both Empirical Mode Decomposition (EMD) and the Hilbert Spectral Analysis (HSA) are given in Huang et al. (1996, 1998 and 1999). The following summary is based on a simplified version given in Huang (2005). The EMD method is necessary to reduce any data from non-stationary and nonlinear processes into simple oscillatory function that will yield meaningful instantaneous frequency through the Hilbert transform. Contrary to almost all the previous decomposing methods, EMD is empirical, intuitive, direct, and adaptive, with the *a posteriori* defined basis derived from the data. The decomposition is designed to seek the different simple intrinsic modes of oscillations in any data based on the principle of scale separation. The data, depending on its complexity, may have many different coexisting modes of oscillation at the same

time. Each of these oscillatory modes is represented by an Intrinsic Mode Function (IMF) with the following definitions:

(a) in the whole data set, the number of extrema and the number of zero-crossings must either equal or differ at most by one, and

(b) at any point, the mean value of the envelope defined by the local maxima and the envelope defined by the local minima is zero.

The IMF is a counter part to the simple harmonic function, but it is much more general: instead of constant amplitude and frequency, IMF can have both variable amplitude and frequency as functions of time. This definition is inspired by the simple example of constant plus sinusoidal function given above. The total number of the IMF components is limited to $\ln_2 N$, where N is the total number of data points. It satisfies all the requirements for a meaningful instantaneous frequency through Hilbert transform.

Pursuant to the above definition for IMF, one can implement the needed decomposition of any function, known as sifting, as follows: Take the test data; identify all the local extrema; divide the extrema into two sets: the maxima and the minima. Then connect all the local maxima by a cubic spline line to form an upper envelope. Repeat the procedure for the local minima to form a lower envelope. The upper and lower envelopes should encompass all the data between them. Their mean is designated as m_1 , and the difference between the data and m_1 is designated as, h_1 , a proto-IMF:

$$X(t) - m_1 = h_1. \quad (11)$$

Ideally, h_1 should satisfy the definition of an IMF by construction of h_1 described above, which should have made it symmetric and having all maxima positive and all minima negative. Yet, in changing the local zero from a rectangular to a curvilinear coordinate system some inflection points could become additional extrema. New extrema generated this way actually reveal the hidden modes missed in the initial treatment. The sifting process sometimes can recover signals representing low amplitude riding waves with repeated siftings.

The sifting process serves two purposes: to eliminate riding waves and to make the wave profiles more symmetric. While the first condition is absolute necessary for Hilbert transform to give a meaningful instantaneous frequency, the second condition is also necessary in case the neighboring wave amplitudes having too large a disparity. As a result, the sifting process has to be repeated many times to reduce the extracted signal an IMF. In the subsequent sifting process, h_1 is treated as the data for the next round of sifting; therefore,

$$h_1 - m_{11} = h_{11}. \quad (12)$$

After repeated sifting, up to k times, h_{1k} :

$$h_{1(k-1)} - m_{1k} = h_{1k}. \quad (13)$$

If h_{1k} becomes an IMF, it is designated as c_1 :

$$c_1 = h_{1k}, \quad (14)$$

the first IMF component from the data. Here one has a

critical decision to make: when to stop. Too many rounds of sifting will reduce the IMF to FM page criterion; too few rounds of sifting will not have a valid IMF. In the past, different criteria have been used, including Cauchy type criterion (Huang et al. 19980), S -number criterion (Huang et al. 2003), fixed-number criterion (Wu and Huang 2004), and etc.

With any stoppage criterion, the, c_1 should contain the finest scale or the shortest period component of the signal. one can, then, remove c_1 from the rest of the data by

$$X(t) - c_1 = r_1. \quad (16)$$

Since the residue, r_1 , contains all longer period variations in the data, it is treated as the new data and subjected to the same sifting process as described above. This procedure can be repeated to all the subsequent r_j 's, and the result is

$$\begin{aligned} r_1 - c_2 &= r_2, \\ &\dots \\ r_{n-1} - c_n &= r_n \end{aligned} \quad (17)$$

The sifting process should stop when the residue, r_n , becomes a constant, a monotonic function, or a function contains only a single extrema, from which no more IMF can be extracted. By summing up Equations (16) and (17), we finally obtain

$$X(t) = \sum_{j=1}^n c_j + r_n. \quad (18)$$

Thus, sifting process produces a decomposition of the data into n -intrinsic modes, and a residue, r_n . When apply the EMD method, a mean or zero reference is not required; EMD needs only the locations of the local extrema. The sifting process generates the zero reference for each component. Without the need of the zero reference, EMD avoids the troublesome step of removing the mean values for the large non-zero mean.

Two special notes here deserve our attention. First, the sifting process offered a way to circumvent the difficulty of define the local mean in a nonstationary time series, where no length scale exists for one to implement the traditional mean operation. The envelope mean employed here does not involve time scale; however, it is local. Second, the sifting process is a Reynolds-type decomposition: separating variations from the mean, except that the mean is a local instantaneous mean, so that the different modes are almost orthogonal to each other, except for the nonlinearity in the data.

Recent studies by Flandrin et al. (2004) and Wu and Huang (2004) established that the EMD is equivalent to a dyadic filter bank, and it is also equivalent to an adaptive wavelet. Being adaptive, we have avoided the shortcomings of using any *a priori*-defined wavelet basis, and also avoided the spurious harmonics that would have resulted. The components of the EMD are usually physically meaningful, for the characteristic scales are defined by the physical data.

Having established the decomposition, we can also identify a new use of the IMF components as filtering. Traditionally, filtering is carried out in frequency space

only. But there is a great difficult in applying the frequency filtering when the data is either nonlinear or non-stationary or both, for both nonlinear and non-stationary data generate harmonics of all ranges. Therefore, any filtering will eliminate some of the harmonics, which will cause deformation of the data filtered. Using IMF, however, we can devise a time space filtering. For example, a low pass filtered results of a signal having n -IMF components can be simply expressed as

$$X_{lk}(t) = \sum_k^n c_j + r_n ; \quad (19)$$

a high pass results can be expressed as

$$X_{hk}(t) = \sum_k^k c_j ; \quad (20)$$

and a band pass result can be expressed as

$$X_{bk}(t) = \sum_b^k c_j . \quad (21)$$

The advantage of this time space filtering is that the results preserve the full nonlinearity and nonstationarity in the physical space.

Having obtained the Intrinsic Mode Function components, one can compute the instantaneous frequency for each IMF component as the derivative of the phase function. And one can also designate the instantaneous amplitude from the Hilbert transform to each IMF component. Finally, the original data can be expressed as the real part, RP, of the sum of the data in terms of time, frequency and energy as:

$$X(t) = RP \sum_{j=1}^n a_j(t) e^{i \int \omega_j(t) dt} . \quad (22)$$

Equation (22) gives both amplitude and frequency of each component as a function of time. The same data, if expanded in a Fourier representation, would have a constant amplitude and frequency for each component. The contrast between EMD and Fourier decomposition is clear: The IMF represents a generalized Fourier expansion with a time varying function for amplitude and frequency. This frequency-time distribution of the amplitude is designated as the Hilbert Amplitude Spectrum, $H(\omega, t)$, or simply the Hilbert spectrum.

From the Hilbert spectrum, we can also define the marginal spectrum, $h(\omega)$, as

$$h(\omega) = \int_0^T H(\omega, t) dt. \quad (23)$$

The marginal spectrum offers a measure of total amplitude (or energy) contribution from each frequency value. It represents the cumulated amplitude over the entire data span in a probabilistic sense.

The combination of the Empirical Mode Decomposition and the Hilbert Spectral Analysis is designated by NASA as the Hilbert-Huang Transform (HHT) for short. Recent studies by various investigators indicate that HHT is a super tool for time-frequency analysis of nonlinear and nonstationary data (Huang and

Attoh-Okine, 2005, Huang and Shen, 2005). It is based on an adaptive basis, and the frequency is defined through the Hilbert transform. Consequently, there is no need for the spurious harmonics to represent nonlinear waveform deformations as in any of the *a priori* basis methods, and there is no uncertainty principle limitation on time or frequency resolution from the convolution pairs based also on *a priori* bases. A summary of the comparison between Fourier, Wavelet and HHT analyses is given in Table 1.

Table 1. Comparisons between Fourier, Wavelet and Hilbert-Huang Transform in Data analysis.

	Fourier	Wavelet	HHT
basis	<i>a priori</i>	<i>a priori</i>	adaptive
frequency	donvolution: global, uncertainty	donvolution: reginal, uncertainty	differentiation: local, certainty
presentation	energy-frequency	energy-time-frequency	energy-time-frequency
nonlinear	no	no	yes
non-stationary	no	no	yes
feature extraction	no	discrete: no continuous: yes	yes
theoretical base	complete	complete	empirical

After this basic development of the HHT method, there are some recent developments, which have either added insight to the results, enhanced the statistical significance of the results, and fixed some shortcomings in the HHT. Some of the recent developments will be summarized later.

3. An Alternative View on Nonlinearity

Having presented the Hilbert spectral analysis, we will explore the alternative view of Hilbert analysis on nonlinearity effects in the data. When one decomposing any data with an *a priori* basis, an inevitable consequence is to have harmonics, which are mathematic artifacts rather than physical entities. Take the water surface waves as an example, which are certainly nonlinear. Therefore, in the traditional view, we have to employ harmonics of the fundamental to fit the nonlinearly distorted profile. Yet, all of the harmonics are not dispersive; they are all bounded waves and have to propagate at the same phase speed as the fundamental. As a result, the wave spectra of water waves based on Fourier analysis is an entangled and inseparable mixture of bounded and free waves. Thus it makes the interpretation of the spectrum extremely difficult for any range other than the energy containing part (see, Huang, et al., 1998, 1999). The intra-wave modulation through Hilbert spectral analysis offers a physically meaningful alternative. A simple example as given by Huang et al (1998) is a mathematic model,

$$x(t) = \cos(\alpha t + \epsilon \sin 2\alpha t), \quad (24)$$

which has an intra-wave modulated instantaneous frequency of

$$\omega(t) = \alpha (1 + 2\varepsilon \cos \alpha t) . \quad (25)$$

This frequency truthfully depicts the behavior of the oscillator. Yet using Fourier representation the data would have to be decomposed into the fundamental and harmonics as

$$x(t) = \left(1 - \frac{\varepsilon}{2}\right) \cos \alpha t + \frac{\varepsilon}{2} \cos 3\alpha t + \dots \quad (26)$$

Although the two representations are equally valid mathematically, the intra-wave approach is obviously more physically meaning. For more complicated cases, examples can be found in Huang et al (1998, 1999).

4. The recent Developments

After considering the basics of HHT analysis, some recent developments in the following areas will be discussed in some details:

- 1) The Normalized Hilbert Transform (NHT) and the direct quadrature (DQ)
- 2) Confidence Limit
- 3) Statistical Significance of IMFs
- 4) Ensemble EMD

4.1. The Normalized Hilbert Transform and the direct quadrature

It is well known that, although the Hilbert transform exists for any function of L^p class, the phase function of the transformed function will not always yield physically meaningful instantaneous frequencies. The limitations have been summarized succinctly in two theorems.

First, in order to separate the contribution of the phase variation into the phase and amplitude parts, the function have to satisfy the limitation stipulated in the Bedrosian theorem (1963), which states that the Hilbert transform for the product of two functions, $f(t)$ and $h(t)$, can be written as

$$H[f(t)h(t)] = f(t)H[h(t)] , \quad (27)$$

only if the Fourier spectra for $f(t)$ and $h(t)$ are totally disjoint in frequency space, and the frequency content of the spectrum for $h(t)$ is higher than that of $f(t)$. This limitation is critical, for we need to have

$$H[a(t) \cos \theta(t)] = a(t) H[\cos \theta(t)] , \quad (28)$$

otherwise, one cannot use Equation (6) to define the phase function, for the amplitude variation would mix with the phase function. Bedrosian theorem requires that the amplitude is varying be so slowly that the frequency spectra of the envelope and the carrier waves are disjoint. This is possible only for trivial cases, for unless the amplitude is constant, any local deviation can be considered as a sum of delta-functions, which has a wide white spectrum. Therefore, the spectrum for varying amplitude would never be totally separate from that of the carrier. This limitation has made the application of the Hilbert transform even to IMFs problematic. To satisfy this requirement, Huang and Long (2003) have

proposed the normalization of the IMFs in the following steps: Starting from an IMF, they first find all the maxima of the IMFs, defining the envelope by spline through all the maxima, and designating the envelope as $E(t)$. Now, normalize the IMF by dividing the IMF by $E(t)$. Thus, they have the normalized function having amplitude always equal to unity, and have circumvented the limitation of Bedrosian theorem.

Second, there is the new restriction given by the Nuttall theorem (1966), which stipulates that the Hilbert transform of cosine is not necessarily the sine with the same phase function for a cosine with an arbitrary phase function. Nuttall gave an energy based error bound, ΔE , defined as the difference between $y(t)$, the Hilbert transform of the data, and $Q(t)$, the quadrature (with phase shift of exactly 90°) of the function as

$$\Delta E = \int_{t=0}^T |y(t) - Q(t)|^2 dt = \int_{-\infty}^0 S_q(\omega) d\omega , \quad (29)$$

in which S_q is Fourier spectrum of the quadrature function. Though the proof of this theorem is rigorous, the result is hardly useful, for it gives a constant error bound over the whole data range. With the normalized IMF, Huang and Long (2003) have proposed a variable error bound based on a simple argument, which goes as follows: compute the difference between squared amplitude of the normalized IMF and unity. If the Hilbert transform is exactly the quadrature, the difference between it and unity should be zero; otherwise, the Hilbert transform cannot be exactly the quadrature. Consequently, the error can be measured simply by the difference between the squared normalized IMF and unity, which is a function of time. Huang and Long (2003) and Huang et al. (2006) have conducted detailed comparisons and found the result quite satisfactory.

Even with the error indicator, we can only know that the Hilbert transform is not exactly the quadrature; we still do not have the correct answer. This prompts a drastic alternative, eschewing the Hilbert transform totally. An exact direct quadrature has been found (Huang et al., 2006), and it would resolve the difficulties associated with the instantaneous frequency computation.

4.2 The confidence limit

The confidence limit for the Fourier spectral analysis is based on the ergodic theory, where the temporal average is treated as the ensemble average. This approach is only valid if the processes are stationary. Huang et al. (2003) has proposed a different approach by utilizing the fact that there are infinite many ways to decompose one given function into difference components. Using EMD, one can still obtain many different sets of IMFs by changing the stoppage criteria. The confidence limit so derived does not depend on the ergodic theory.

From the confidence limit study, Huang et al. (2003) also found the optimal S -number, when the differences reach a local minimum. Based on their experience from different data sets, they concluded that an S -number in the range of 4 to 8 performed well. Logic also dictates that the S -number should not be too high (which would drain all the physical meaning out of the IMF), nor too low (which would leave some riding waves remaining in the resulting IMFs).

4.3 The Statistical Significance of IMFs

The EMD is a method to separate the data into different components by their scales. There is always the question: On what is the statistical significance of the IMFs based? In data containing noise, how can we separate the noise from information with confidence? This question was addressed by both Flandrin et al. (2004) and Wu and Huang (2004) through the study of signals consisting of noise only. Using white noise, Wu and Huang (2004) found the relationship between the mean period and RMS values of the IMFs. Furthermore, from the statistical properties of the scattering of the data, they found the bounds of the data distribution analytically. They concluded that when a data set is analyzed with EMD, if the mean period-RMS values exist outside the noise bounds, the components most likely contains signal, otherwise, a component could be resulted only from noise. Therefore, the components with their mean period-RMS values exceeding the noise bounds are statistically significant.

4.4 Ensemble EMD

One of the major problems existed in EMD is scale mixing: an IMF often contains local oscillations with dramatically different frequencies/scales (Huang et al 1999). Previous solution to that was introducing the intermittency check in which the frequency/scale range is subjectively determined. While such an approach works well in many cases, it also has side effect such as reducing adaptation of the EMD method.

Recently, a new Ensemble Empirical Mode Decomposition (EEMD) method is presented. This new approach consists of an ensemble of decompositions of data with added white noise, and then treats the resultant mean as the final true result. Finite, not infinitesimal, amplitude white noise is necessary to force the ensemble to exhaust all possible solutions in the sifting process, thus requiring the different scale signals to collate in the proper intrinsic mode functions (IMF) dictated by the dyadic filter banks. The effect of the added white noise is to present a uniform reference frame in the time-frequency and time-scale space; and, therefore, the added noise provides a natural reference for the signals of comparable scale to collate in one IMF. With this ensemble mean, the scale can be clearly and naturally separated without any *a priori* subjective criterion selection, such as in the intermittence test for the original EMD algorithm. This new approach fully utilizes the statistical characteristics of white noise to perturb the data in its true solution neighborhood, and then cancel

itself out (via ensemble averaging) after serving its purpose; therefore, it represents a substantial improvement over the original EMD and qualifies for a truly noise-assisted data analysis (NADA) method.

5. Mathematical Problem Associated with HHT

HHT is an empirically based method. This limitation is not severe when we consider it as a data analysis tool, for all the data are empirical values without analytic expressions anyway. We are at the stage of the wavelet analysis in the earlier 80s: producing useful results but waiting for mathematical foundation to rest our case. The outstanding mathematical problems, as listed by Huang (2005), are summarized here. We hope the mathematicians working in wavelet analysis will be interested in this new alternative and help as follows:

- 1) Adaptive data analysis methodology in general
- 2) Nonlinear system identification methods
- 3) Prediction problem for nonstationary processes (end effect)
- 4) Spline problem (best spline implement of HHT, convergence and 2-D)
- 5) Optimization problem (the best IMF selection and uniqueness)
- 6) Approximation problem (Hilbert transform and quadrature)
- 7) Miscellaneous questions concerning the HHT

6. Summary

The combination of EMD and HSA has provided an adaptive method to analyze nonstationary and nonlinear time series. It can perform and enhance most of the traditional data analysis tasks, such as filtering, regressions, and spectral analysis adaptively. Although adaptive signal analysis is long sought goal for the engineering community (Windrows and Stearns, 1985), the requirement here is much more stringent: we have to deal both nonlinearity and nonstationarity; therefore, the simple feedback method used for stationary processes would not be sufficient. This stringent requirement has put the new method on an empirical base at the present time. As far as data analysis is concerned, the lack of analytic expression would not be a problem, for none of the data came in analytical form anyway. Nevertheless, a purely empirical approach will certainly present a problem for a rigorous mathematical proof of the validity of the method. It is an earnest hope that the usefulness of the method will eventually interested the mathematicians to examine the method critically and constructively, so that the method will find its mathematical foundation established rigorously similar to what Daubechies (1992) had done for the Wavelet analysis.

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